

## Lab 6 (associated with Hw 6): Dynamic response with harmonic forcing

The objective of this laboratory is to develop physical intuition into how a forcing function effects the behavior of a physical system governed by a second-order, linear, ODE.

### Lab 6.1 Effect of forcing function frequency ( $\Omega$ ) on the dynamic response of a pogo stick.

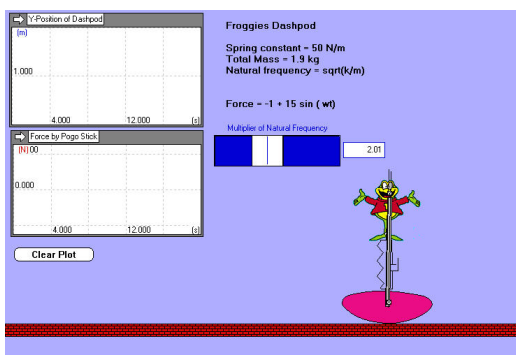
The power/energy-rate principal relates  ${}^N P^S$  (the power of a system  $S$  in a Newtonian reference frame  $N$ ) with the time-rate of change of  ${}^N K^S$  (the kinetic energy of  $S$  in  $N$ ) as

$${}^N P^S = \frac{d {}^N K^S}{dt}$$

The power associated with  $\vec{F}^P$  (a force applied to a point  $P$ ) is denoted  ${}^N P^{\vec{F}^P}$  and is defined in terms of  ${}^N \vec{v}^P$  (the velocity of  $P$  in  $N$ ) as

$${}^N P^{\vec{F}^P} \triangleq \vec{F}^P \cdot {}^N \vec{v}^P$$

In view of these equations and the definition of the vector dot-product, one may see that  $\vec{F}^P$  adds power to a system (increases kinetic energy) when  $\vec{F}^P$  is applied in the same direction as  ${}^N \vec{v}^P$ . Alternately,  $\vec{F}^P$  removes power from a system (decreases kinetic energy) when  $\vec{F}^P$  is applied in the direction opposite  ${}^N \vec{v}^P$ .



To begin, double-click on the file `HarmonicForcingPogoStick.wm2d`. To answer each question with Working Model, click the **Reset** button (if necessary) and click and drag the slider that controls  $\Omega/\omega_n$  (the ratio of the forcing frequency to the system's natural frequency). To start the simulation, click the **Run** button, and to stop it, click the **Stop** button.

- When the forcing frequency  $\Omega$  is approximately equal to the system's natural frequency  $\omega_n$ , i.e.,  $\frac{\Omega}{\omega_n} \approx 1$ , the pogo stick jumps **very high/high/low/none**.
- When the forcing frequency  $\Omega$  is much higher than the system's natural frequency  $\omega_n$ , i.e.,  $\frac{\Omega}{\omega_n} > 2$ , the pogo stick jumps **very high/high/low/none**.
- When the forcing frequency  $\Omega$  is much lower than the system's natural frequency  $\omega_n$ , i.e.,  $\frac{\Omega}{\omega_n} < 0.5$ , the pogo stick jumps **very high/high/low/none**.
- Explain your observations based on the power/energy-rate principle.

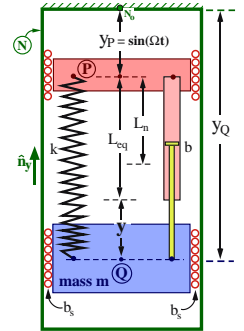
- Optional: What happens when the center of mass position is moved?

## Lab 6.2 Harmonic forcing of a mass-spring-damper system

Homework 5.4 showed that when the Scotch-yoke mechanism moved  $P$  so that  $y_P(t) = \bar{A} \sin(\Omega t)$ , the equation of motion governing  $y(t)$  (when  $b_s=0$ ) was

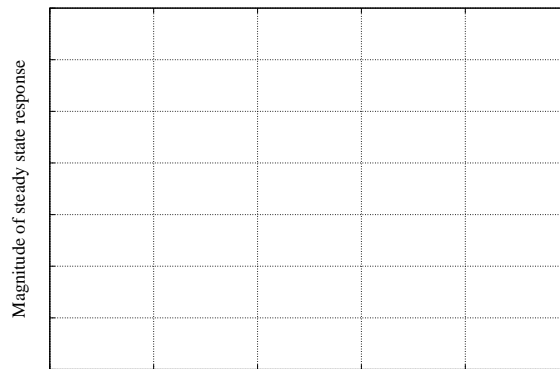
$$\ddot{y} + \frac{b}{m} \dot{y} + \frac{k}{m} y = \bar{A} \Omega^2 \sin(\Omega t)$$

Quantity	Symbol	Type
Mass of $Q$	$m$	Constant
Linear spring constant of spring connecting $P$ and $Q$	$k$	Constant
Natural length of spring connecting $P$ and $Q$	$L_n$	Constant
Static equilibrium length of spring connecting $P$ and $Q$	$L_{eq}$	Constant
Earth's gravitational acceleration	$g$	Constant
Linear damper constant of damper connecting $P$ and $Q$	$b$	Constant
Linear damper constant associated with $Q$ 's sliding in $N$	$b_s$	Constant
Measure of $Q$ 's equilibrium position from $P$	$y$	Variable
Measure of $P$ 's position from a line fixed in $N$	$y_P$	<b>Specified</b>
Amplitude of harmonic forcing	$A$	Constant
Frequency of harmonic forcing	$\Omega$	Constant



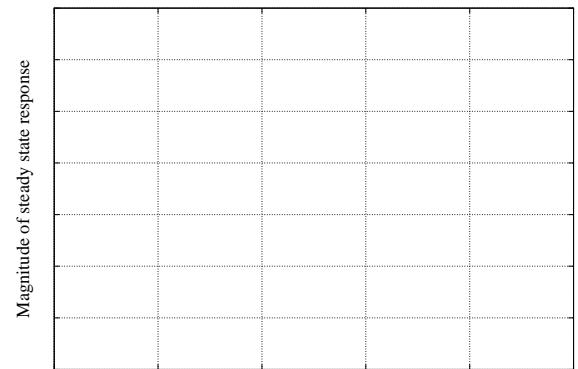
- (a) Complete the following sketches. Note:  $y(t)$  characterizes how  $Q$  moves relative to  $P$  and  $y_Q(t) \triangleq y_P(t) + y(t)$  characterizes how  $Q$  moves relative to  $N$ .

$|y_{ss}(t)|$  vs.  $\Omega$



Forcing frequency

$|y_{Q_{ss}}(t)|$  vs.  $\Omega$



Forcing frequency

- (b) The particle  $Q$  moves very little in  $N$  at **low/high** (circle one) frequency whereas at **low/high** frequency,  $Q$  appears to be rigidly connected to  $P$ . The most energetic motion of  $Q$  in  $N$  occurs when  $\Omega \approx$   .